

Forecast Densities for Economic Aggregates from Disaggregate Ensembles

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Index construction

- ▶ Suppose that a set of N disaggregate prices $d = 1, \dots, N$ is simulated as:

$$y_{t,d} = \mu_{t,d} + \rho_{t,d}y_{t,d} + \epsilon_{t,d}, \quad t = 1, \dots, T, \quad \epsilon_{t,d} \sim N(0, \sigma_{t,d}^2). \quad (1)$$

where $y_{t,d} = (p_{t,d} - p_{t-1,d})$.

- ▶ Then, define an aggregate index as:

$$y_t = \sum_{d=1}^N w_{t,d} y_{t,d}, \quad w_{t,d} > 0, \quad \sum_d w_{t,d} = 1. \quad (2)$$

- ▶ Example: inflation, GDP, ...

Model uncertainty issues

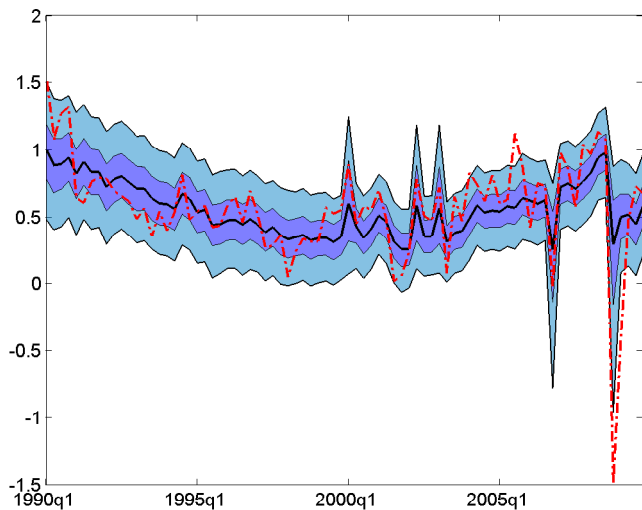
- ▶ Index weights (d, N) could be unknown and change next period (Lutkepohl, 2009 and 2010).
- ▶ Disaggregate i could be related to past values of disaggregate j (van Garderen *et al*, 2000).
- ▶ Time variation in the weights and model parameters introduces nonlinearities (Groen *et al.*, 2009).
- ▶ Data and weights could contain non trivial errors (Ravazzolo and Vahey, 2009, on Australia inflation).
- ▶ Aggregate might not have Gaussian errors (Cheung and Chung (2009) for long memory and Garch effects).
- ▶ **How to forecast future inflation?**

Ensemble modeling

- ▶ Uncertainty about model specifications (e.g. initial conditions, data, parameters, and boundary conditions) in dynamic, stochastic or nonlinear (chaotic) systems.
- ▶ Approximate (future) unknown non-linear non-Gaussian system with combination of (density) forecasts from large number of locally-linear models with time-varying weights.
- ▶ Use forecast density combination technology (Wallis, 2010; Hall and Mitchell, 2005; Jore *et al.*, 2010; Kascha and Ravazzolo, 2010) to construct ensemble predictive densities.
- ▶ The true model is not be included in the model space (Geweke, 2009).
- ▶ **Results:** our ensemble outperforms aggregate benchmarks in density forecasting both in simulation exercises and in an empirical application with US PCE inflation.

- ▶ Density forecasting
- ▶ Ensemble methodology
- ▶ Application
- ▶ Results
- ▶ Conclusions
- ▶ NB policy tool

Density forecasts (fanchart)



Evaluating Predictive Densities

Problem: The true density is never observed.

There are two main approaches in the literature:

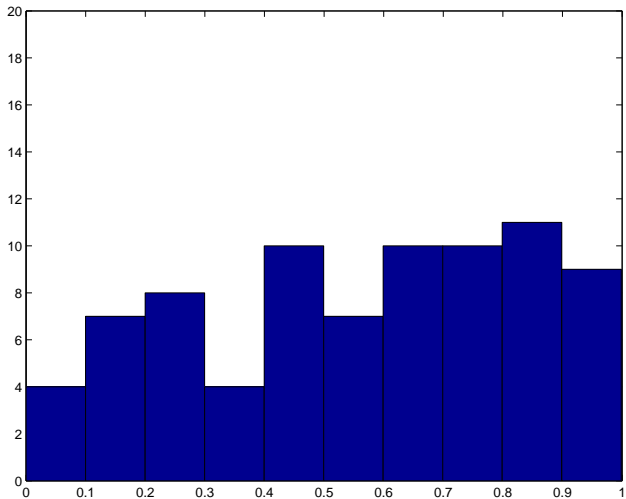
- ▶ Test whether a predictive density is correctly specified using Probability Integrated Transform Scores.
- ▶ Evaluate multiple, possibly misspecified and nested models:
 - ▶ Economic value of forecasts (finance).
 - ▶ With respect to a benchmark density.
 - ▶ Kullback-Leibler Information Criterion.
 - ▶ Continuous Ranked Probability Scores

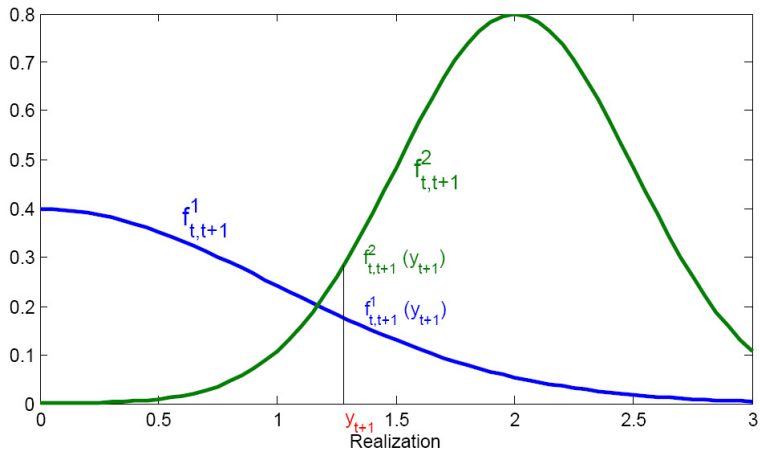
A forecast density is preferred if the density is correctly calibrated, regardless of the forecaster's loss function:

The *PITS* are:

$$z_{\tau} = \int_{-\infty}^{\pi_{\tau}} g(u) du.$$

The *PITS* should be both uniformly distributed, and independently and identically distributed if the forecast densities are correctly calibrated. Hence, calibration evaluation requires the application of tests for goodness-of-fit and independence.





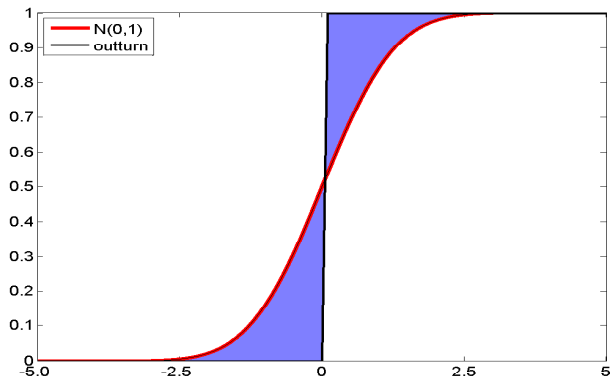
The KLIC distance between the true density $f(\pi_\tau)$ of π_τ and the i th density forecast, $f(\pi_\tau | I_{i,\tau})$, for π_τ conditional on information up to time $\tau - 1$ is defined as

$$\begin{aligned}\text{KLIC}_\tau &= \int f(\pi_\tau) \ln \frac{f(\pi_\tau)}{f(\pi_\tau | I_{i,\tau})} d\pi_\tau \\ &= E[\ln f(\pi_\tau) - \ln(\pi_\tau | I_{i,\tau})].\end{aligned}$$

The latter term on the right hand side can be estimated by the average logarithmic score or “log-score”

$$\ln S^i := -\frac{1}{T^e} \sum_{t=T^s}^T \ln(\pi_\tau | I_{i,\tau}),$$

$$T^e = T - T^s + 1.$$



- ▶ The CRPS is measured as the difference between the predicted and actual cumulative distribution. The (positive) score approaches zero as the predictive density converges on the true (but unobserved) density.
- ▶ In formula:

$$CRPS = \int_{-\text{inf}}^{+\text{inf}} (F(h) - I(h \geq \pi_o))^2 dh \quad (3)$$

where $I(A) = 1$ if A is true.

- ▶ Approximated (Panagiotelis and Smith 2008) by:

$$CRPS = E_F |\pi - \pi_o| - 0.5 E_F |\pi - \pi'| \quad (4)$$

where E_F is the expectation for the predictive F , π and π' are independent random draws from the predictive, and π_o is the observed outturn.

- ▶ Given $i = 1, \dots, N$ different model specifications:

$$p(\pi_\tau) = \sum_{i=1}^N w_{i,\tau} g(\pi_\tau | I_{i,\tau}), \quad \tau = \underline{\tau}, \dots, \bar{\tau}. \quad (5)$$

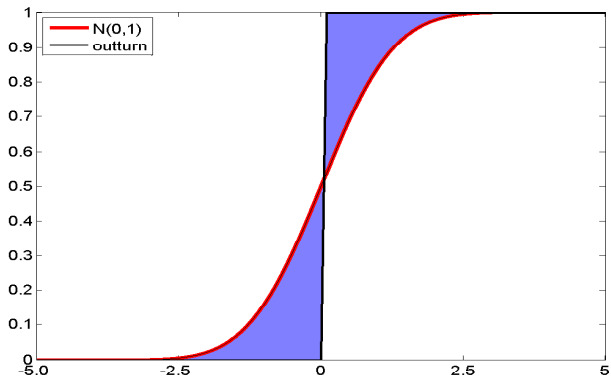
- ▶ Where $g(\pi_\tau | I_{i,\tau})$ is the **density** of interest from component i , $i = 1, \dots, N$.

- ▶ And $w_{i,\tau} \geq 0$, $\sum_i w_{i,\tau} = 1$;

$$w_{i,\tau} = \frac{[\sum_{\underline{\tau}}^{\tau-1} X(g(\pi_\tau | I_{i,\tau}))]}{\sum_{i=1}^N [\sum_{\underline{\tau}}^{\tau-1} X(g(\pi_\tau | I_{i,\tau}))]}, \quad \tau = \underline{\tau}, \dots, \bar{\tau}.$$

- ▶ X is a CRPS based measure (Continuous Ranked Probability Scores).
- ▶ Generation of combined densities with component model weights varying through time.

CRPS



- ▶ Inflation predictive densities for measured inflation based on disaggregate inflation series (**uncertainty on model specifications**).
- ▶ Construct predictive densities for measured inflation from [AR(2)] (dis)aggregates $g(\pi_\tau | I_{i,\tau})$, $i = 1, \dots, N$ using moving window estimation (**locally-linear**).
- ▶ Ensemble these predictive densities via linear opinion pool (**non-linear non-Gaussian system**) to forecast 1-step ahead headline PCE deflator inflation:
$$p(\pi_\tau) = \sum_{i=1}^N w_{i,\tau} g(\pi_\tau | I_{i,\tau}).$$
- ▶ Correct the bias to produce predictive densities for measured inflation using a $\tau - \underline{\tau} = 20$ quarter moving window.

Simulation

- ▶ Two disaggregates $d = 1, 2$ are simulated as:

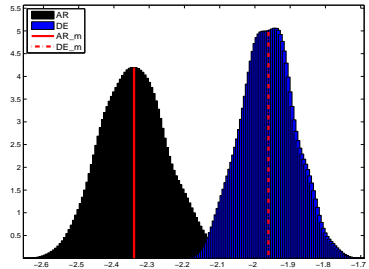
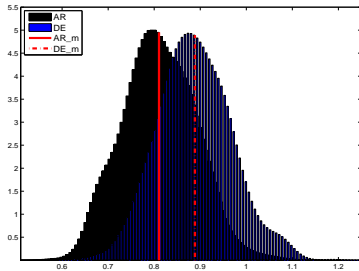
$$y_{t,d} = \mu_{t,d} + \rho_{t,d}y_{t,d} + \epsilon_{t,d}, \quad t = 1, \dots, T, \quad \epsilon_{t,d} \sim N(0, \sigma_{t,d}^2). \quad (6)$$

- ▶ The aggregate is then computed as:

$$y_t = \sum_d w_{t,d} y_{t,d}, \quad w_{t,d} > 0, \quad \sum_d w_{t,d} = 1. \quad (7)$$

- ▶ $T = 120$; initial sample period=40; training period= 20 forecasts; OOS=60 observations. Simulation=1000 times.
- ▶ **Time varying means, standard deviations and weights:** two breaks at time $t = 20$ and $t = 60$ on $\mu_{20,d}$ and $\mu_{60,d}$, and $\sigma_{20,d}$ and $\sigma_{60,d}$, time-varying [AR] weights.
- ▶ AR(1) benchmark for aggregate.
- ▶ Time varying weights and parameters, non-linear non-Gaussian system, true model unknown.
- ▶ Two disaggregates, independent disaggregates.

RMSPE - LS



Quarterly Personal consumption expenditures (PCE) inflation (and disaggregate series) over the sample 1975Q1-2009Q4.

Group 1:

16 disaggregates: Motor vehicles and parts - Furnishings and durable household equipment - Recreational goods and vehicles, Other durable goods - Food and beverages - Clothing and footwear - Gasoline and other energy goods - Other nondurable goods - Housing and utilities - Health care - Transportation services - Recreation services - Food services and accommodations - Financial services and insurance - Other services - Final consumption expenditures of nonprofit institutions serving households.

Application: US PCE inflation forecasting

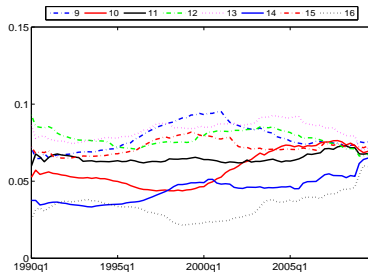
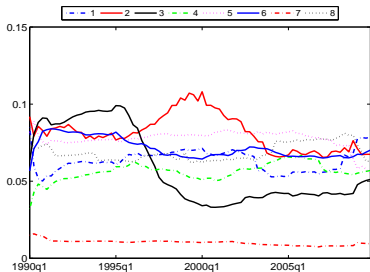
- ▶ Out-of-sample period: 1990Q1-2009Q4.
- ▶ Training period: 1985Q1-1989Q4.
- ▶ Estimation: moving window of 40 observations.
- ▶ Benchmarks: AR(2) and IMA for PCE.
- ▶ Disaggregate ensemble: DE11 based on AR(2) models for the 16 disaggregates.
- ▶ Geweke and Amisano (2009) and Mitchell and Wallis (2010) apply absolute and relative measures.
- ▶ *Absolute*: Test whether a predictive density is correctly specified (Diebold, Gunther and Tay, 1998; **Berkowitz 2001**, **Anderson-Darling**, **Pearson chi-squared**, **Ljung-Box tests**).
- ▶ *Relative*: based on the KLIC distance and rewards models which on average give higher probability to events which have actually occurred (**Mitchell and Hall, 2005** and **Amisano and Giacomini, 2007**).

Density forecast performance

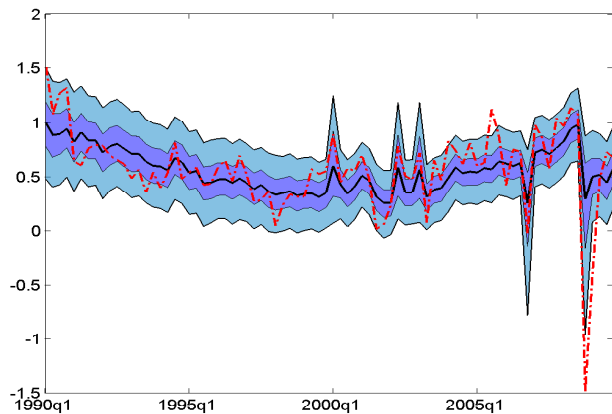
| | LR3 | AD | χ^2 | LB | LS | LS_test |
|-----|-------------------|--------------|--------------|--------------|--------------|--------------|
| DE | 0.051 | 0.097 | 0.408 | 0.520 | 0.064 | 0.000 |
| | Individual models | | | | | |
| AR2 | 0.000 | 0.000 | 0.000 | 0.504 | -0.465 | |
| IMA | 0.014 | 0.000 | 0.000 | 0.871 | -0.095 | 0.000 |

LR3=Berkowitz (2001), AD=Anderson-Darling, χ^2 =Pearson chi-squared,
LB=Ljung-Box; LS=log scores.

DE11's weights



DE11 interval forecasts



- ▶ John Kay (FT, September 21 2010): “There will always be a demand for forecasts, so there will always be a supply. But the reputation of economic forecasters, like other quacks and charlatans, depends more on the slickness of their presentations than the value of their work”.
- ▶ Does he mean **POINT** forecasts?
- ▶ Density forecasting is a necessary input into economic decision making (Granger and Pesaran, 2000).

Conclusions

- ▶ Conventional view: **POINT** forecasting economic aggregate with disaggregates does not work, although used routinely by monetary policy makers.
- ▶ Our focus is on **DENSITY** forecasting with model uncertainty and incomplete component model space.
- ▶ Density ensemble strategy works well in Monte Carlo and in PCE application.
- ▶ Further applications:
 - ▶ Larger number of inflation disaggregates and international comparison.
 - ▶ Euro-area GDP.
 - ▶ Forecasting disaggregates with disaggregates.

Norges Bank core inflation measure

- ▶ NB applies the methodology to a relative large set of disaggregate CPI inflation (from 40 to 45 disaggregates) to construct a core inflation measure.
- ▶ NB forecasts what knows, discarding noise. This can be interpreted as a definition of core inflation measure.
- ▶ It allows to understand whether a shock to a specific component has a pass throw mechanism to the inflation process.

Norges Bank MP2010/3

